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<input type="checkbox"/>	L9	4553899.pn.	2
<input type="checkbox"/>	L8	4382743.pn.	2
<input type="checkbox"/>	L7	('20040210342' '20040105746' '20010051085' '6641355' '6558102' '5340187' '4706779' '4201511' '3915429' '3635636' 'EP 1384698A' 'EP 568758A')!.ABPN1,NRPN,PN,TBAN,WKU.	23
<input type="checkbox"/>	L6	rotating and L5	320
<input type="checkbox"/>	L5	rotat\$3 and L4	603
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<input type="checkbox"/>	L3	gantry robot and lift	73
<input type="checkbox"/>	L2	double lift	373
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<input type="checkbox"/>	L1	lift\$3 (truck or vehicle or robot) and telecop\$3 and load	3

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**Results Key:****JNL** = Journal or Magazine   **CNF** = Conference   **STD** = Standard

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**1 Manipulator system for constructing overhead distribution lines***Ohnishi, H.; Yokoyama, H.; Waki, S.; Mochizuki, K.; Toratani, T.; Erukawa, H.; Mukai, F.; Yokoyama, S.; Kojima, H.; Kaihara, N.;*

Robot and Human Communication, 1992. Proceedings., IEEE International Workshop on , 1-3 Sept. 1992

Pages:235 - 240

**IEEE CNF**

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**2 PLC control systems for the remote control of cranes and manipulators***Hughes, S.;*

Advances in Programmable Logic Controllers, IEE Colloquium on , 24 Feb 1992

Pages:5/1 - 5/4

**IEE CNF**

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